

**AUR**

**Automation and Robotics research group**



**Dipartimento di Ing. Civile e Ing. Informatica  
DICII  
Università degli studi di Roma  
"Tor Vergata"**

**Laurea Magistrale in Ing. Robotica e dell'Automazione  
&  
Laurea in Ing. Informatica, indirizzo Robotica e dell'Automazione**

**<http://control.disp.uniroma2.it/ARgroup/>**

Staff:

- Prof. Alessandro Astolfi
- PhD. Daniele Carnevale
- PhD. Sergio Galeani
- Prof. Osvaldo Maria Grasselli
- PhD. Francesco Martinelli
- Prof. Laura Menini
- Prof. Salvatore Nicosia
- Prof. Antonio Tornambè
- Prof. Luca Zaccarian

Know-how:*Nonlinear Control**Robotics**Estimation**Modeling and Identification**Supply chain**Vision and localization**Saturated actuators**Observers**Optimal Control**Periodic Systems**Adaptive Control**Hybrid Systems**Robust Control**Smart actuators**Network Controlled Systems**Systems with Impacts**Digital Control**UAV - UGV**Biological systems*

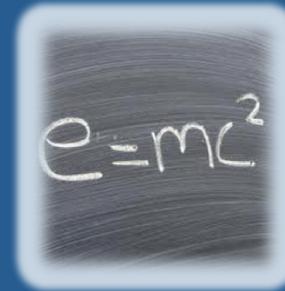
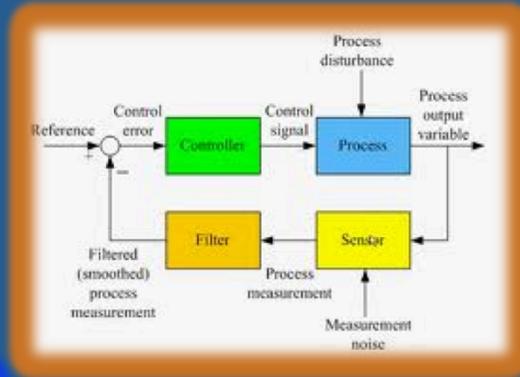
## Daniele Carnevale

- Ricercatore nel settore disciplinare ING-INF04 (Automazione) in servizio da Dicembre 2008 presso la facoltà di Ingegneria di Roma Tor Vergata
- Docente del corso di Controlli Automatici e Fondamenti di Automatica
- Autore di circa 50 articoli su riviste e atti di congressi internazionali “peer-reviewed”
- Responsabile del programma di ricerca “Study and application of innovative software architectures and nonlinear control techniques for the FTU real-time control system”, ENEA-FTU di Frascati e l'associazione EURATOM/ENEA
- Collaborazioni con: University of California, Santa Barbara(UCSB), Imperial College, London (UK), University of Leicester (UK), Culham Science Centre (UK), Johannes Kepler University, Linz (Austria), LAAS-CNRS, Toulouse (France), University of Melbourne (Australia)
- Interessi di ricerca: stima, controllo nonlineare, ottimizzazione, modellazione, robotica, networked control, sistemi ibridi.

**Ufficio:** A4-06, Edificio di Ing. dell'Informazione, Università di Roma “Tor Vergata”,  
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fisica e matematica

teoria del controllo



elettronica



informatica

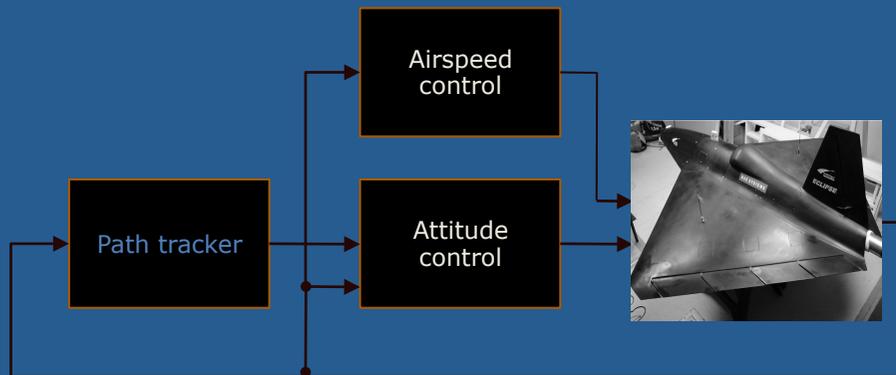


telecomunicazioni



meccanica

# AEROSPACE



Flight control

Cruise control and vibration analysis



Satellite stabilization (reaction wheel)

## ***AUTOMOTIVE***



Electrical and combustion engines power control

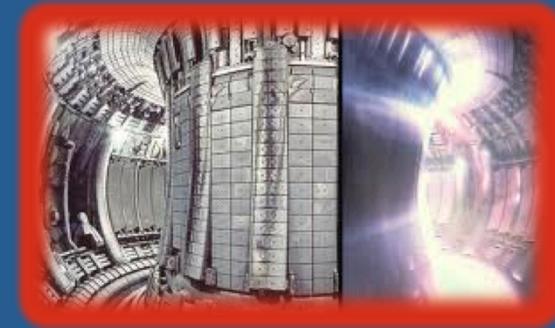
Modeling of vibration effects on human spine



Magnetorheological suspensions

## Clean Energy

Nuclear Fusion: plasma confinement in Tokamaks



Extremum seeking techniques for on-line optimization of solar trackers

Distributed optimization for smart buildings



## ***BIOLOGICAL SYSTEMS***



Approximated (dynamically) optimal control for nonlinear bioreactors

Modeling and control of diabetes



Distributed sensors and data mining for crop monitoring and control of fermentation process

# ROBOTICS



Rehabilitation robotics, systems for gesture recognition

Aerial autonomous vehicles (video surveillance, gaming)



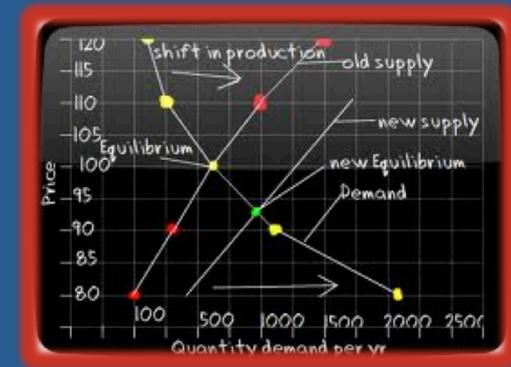
Ground autonomous vehicles (cleaning, transport, harvesting)

# INDUSTRY



Supply chain

Modelling and optimization (dynamic demand and supply)



Industrial robotics and vision systems